

# ICL-GNSS 2021, June 1-3, 2021

## AGENDA

**All times are in EEST (GMT+3)**

### Tuesday, June 1, 2021

10:00am - 10:20am            **Opening**

Session Chair: Jari Nurmi, Tampere University

10:20am - 11:00am            **Localization 1**

Session Chair: Joaquín Torres-Sospedra, Universitat Jaume I

10:20            WALLSY: The UWB and SmartMesh IP enabled Wireless Ad-hoc Low-power Localization SYstem  
Sabin C Gheorghiu, Rene H Molnar, Kazmer Nagy-Betegh, Ryan C Grammenos  
University College London, United Kingdom

10:40            Outdoor Ranging and Positioning based on LoRa Modulation  
Pascal Müller<sup>1</sup>, Hannes Stoll<sup>1</sup>, Luciano Sarperi<sup>1</sup>, Christof Schüpbach<sup>2</sup>  
1) ZHAW School of Engineering, Switzerland  
2) armasuisse Science + Technology, Switzerland

11:00am - 12:00pm            **Keynote: Eda Marchetti**, Centro Competenza Cybersecurity Toscano

Session Chair: Joaquín Torres-Sospedra, Universitat Jaume I

12:00pm - 12:20pm            Break

12:20pm - 1:40pm            **GNSS1**

Session Chair: Heidi Kuusniemi, University of Vaasa

12:20            Efficient Multi-Hypothesis Tests for Extended Coherent Acquisition Using Modified Linear Feedback Shift Register Secondary Codes  
J. Rossouw van der Merwe<sup>1</sup>, Heike Dorner<sup>1</sup>, Xabier Zubizarreta<sup>2</sup>, Alexander Rügamer<sup>1</sup>, Ivana Lukcin<sup>1</sup>, Daniel Rubino<sup>1</sup>, Wolfgang Felber<sup>1</sup>  
1) Fraunhofer IIS, Germany; 2) ALOR Tech, Spain

12:40            Performance Limits and Benefits of Adaptive Autoregressive Kalman Filters for GNSS Scintillation-Robust Carrier Tracking  
Sergi Locubiche-Serra, Gonzalo Seco-Granados, José A. López-Salcedo  
Universitat Autònoma de Barcelona (UAB), IEEC-CERES, Spain

13:00 Adaptive Techniques in Scalar Tracking Loops with Direct-State Kalman-Filter  
Iñigo Cortés<sup>1</sup>, Pablo Marín<sup>1</sup>, Johannes Roussouw van der Merwe<sup>1</sup>, Elena Simona Lohan<sup>2</sup>, Jari Nurmi<sup>2</sup>, Wolfgang Felber<sup>1</sup>  
1) Fraunhofer IIS, Germany; 2) Tampere University, TAU, Finland

13:20 Sub-Band AGC-Based Interference Mitigation  
Fabio Garzia, J. Rossouw van der Merwe, Alexander Rügamer, Santiago Urquijo, Simon Taschke, Wolfgang Felber  
Fraunhofer IIS, Nordostpark 84, Nuremberg, Germany

1:40pm - 3:00pm Exhibit break and lunch

3:00pm - 4:00pm **5G**

Session Chair: Aleksandr Ometov, Tampere University

15:00 Neural Network Fingerprinting and GNSS Data Fusion for Improved Localization in 5G  
Roman Klus, Jukka Talvitie, Mikko Valkama  
Tampere University, Finland

15:20 5G Positioning Based on the Wideband Electromagnetic Vector Antenna  
Bo Sun<sup>1</sup>, Bo Tan<sup>1</sup>, Wenbo Wang<sup>1</sup>, Mikko Valkama<sup>1</sup>, Christophe Morlaas<sup>2</sup>, Elena Simona Lohan<sup>1</sup>  
1) Tampere University, Finland; 2) ENAC, France

15:40 A combined Ray Tracing simulation environment for hybrid 5G and GNSS positioning  
Ivana Lukcin<sup>1</sup>, Phuong Bich Duong<sup>1</sup>, Katrin Dietmayer<sup>1</sup>, Sheikh Usman Ali<sup>2</sup>, Sebastian Kram<sup>1</sup>, Jochen Seitz<sup>1</sup>, Wolfgang Felber<sup>1</sup>  
1) Fraunhofer IIS, Germany; 2) Technische Universität München (TUM), Germany

4:00pm - 4:20pm Break

4:20pm - 5:00pm **SS Collaborative positioning**

Session Chair: Alex Minetto, Politecnico di Torino

Session Chair: Jordi Vilà-Valls, ISAE-SUPAERO/University of Toulouse

16:20 Smartphone Distance Estimation Based on RSSI-Fuzzy Classification Approach  
Pavel Pascacio<sup>1,2</sup>, Sven Casteleyn<sup>1</sup>, Joaquín Torres-Sospedra<sup>3</sup>  
1) Universitat Jaume I, Spain; 2) Tampere University, Finland; 3) UBIK Geospatial Solutions S.L., Spain

16:40 A Multidimensional Scaling Approach for Seamless Indoor/Outdoor Cooperative GNSS Navigation  
Ali Naouri<sup>1</sup>, Lorenzo Ortega<sup>2</sup>, Jordi Vilà-Valls<sup>1</sup>, Eric Chaumette<sup>1</sup>  
1) ISAE-SUPAERO/University of Toulouse, France; 2) TESA, France

### **Wednesday, June 2, 2021**

10:00am - 11:00am                    **Antennas**

Session Chair: Sarang Thombre, FGI

- 10:00                    Multibeam antenna array and software switching for low-complexity low-cost GNSS beamforming  
Nabanita Sengupta<sup>1</sup>, J. Rossouw van der Merwe<sup>1</sup>, Alexander Koelplin<sup>2</sup>, Alexander Ruegamer<sup>1</sup>, Matthias Kuhl<sup>2</sup>, Wolfgang Felber<sup>1</sup>  
1) Fraunhofer IIS, Germany  
2) 2) Hamburg University of Technology, TUHH, Hamburg, Germany
- 10:20                    MAGICA project: Development of a Multi-frequency Automotive GNSS Integrated Cost effective Antenna  
Evgenii Filatov<sup>1</sup>, Marco Antonio Vélez<sup>1</sup>, Joan Gemio<sup>1</sup>, Jose Javier Vicente<sup>1</sup>, Roser Capdevila<sup>1</sup>, Laura Tantinyà<sup>1</sup>, Alberto Gil<sup>2</sup>, Adrián Cardalda<sup>3</sup>, Daniel Baños<sup>1</sup>, Pere Mogas<sup>1</sup>, Joaquín Reyes<sup>4</sup>  
1) FICOSA International; 2) SEAT; 3) Rohde & Schwarz GmbH & Co; 4) GSA
- 10:40                    Algorithm for direction finding using spinning and omnidirectional antennas that uses all available information  
Matti Raitoharju  
Patria, Finland

11:00am - 12:00pm                    **Keynote: Cyril Botteron**, SpacePNT

Session Chair: Simona Lohan, TAU

12:00pm - 12:20pm                    Break

12:20pm - 1:40pm                    **Localization 2**

Session Chair: Joaquín Torres-Sospedra, Universitat Jaume I

- 12:20                    Feasibility of Standalone TDoA-based Localization Using LoRaWAN  
Ruthwik Muppala<sup>1</sup>, Abhinav Navnit<sup>1</sup>, Deeksha Devendra<sup>1</sup>, Eustachio Roberto Matera<sup>2</sup>, Nicola Accettura<sup>3</sup>, Aftab M. Hussain<sup>1</sup>  
1) PATRIoT Lab, IIIT Hyderabad, India  
2) 2) Abbia GNSS Technologies, Toulouse, France  
3) 3) LAAS-CNRS, Universite de Toulouse, CNRS, Toulouse, France
- 12:40                    Comparison of I/Q- and Magnitude-based UWB Channel Impulse Responses for Device-free Localization  
Marco Cimdins<sup>1</sup>, Sven Ole Schmidt<sup>1</sup>, Horst Hellbrück<sup>1,2</sup>  
1) Technische Hochschule Lübeck, Germany; 2) University of Luebeck, Germany
- 13:00                    Locating the source in wireless sensor networks with unknown start transmission time  
Huijie Zhu<sup>1</sup>, Sheng Liu<sup>2</sup>, Wei Xu<sup>3</sup>, Zhiqiang Yao<sup>4</sup>, Zheng Peng<sup>2</sup>

- 1) Science and Technology on Communication Information Security Control Laboratory, No. 36 Research Institute of China Electronics Technology Group Corporation
- 2) School of Mathematics and Computational Science of Xiangtan University
- 3) Changsha Technology Research Institute of Beidou Industry Safety
- 4) School of Automation and Electronic Information of Xiangtan University

13:20 Towards state-full positioning of mobile subscribers through advanced cellcoverage modeling technique  
Artjom Lind, Amnir Hadachi  
ITS Lab, Institute of Computer Science, University of Tartu, Estonia

1:40pm - 3:00pm Exhibit break and lunch

3:00pm - 4:20pm **GNSS2**

Session Chair: Heidi Kuusniemi, University of Vaasa

15:00 Message-to-Satellite Allocation Strategies for Long GNSS Messages and application to the Galileo High Accuracy Service  
Tommaso Senni<sup>1</sup>, Ignacio Fernández-Hernández<sup>2</sup>, Simòn Cancela<sup>3</sup>  
1) RHEA group for European Commission, Netherlands; 2) European Commission, Brussels; 3) GMV, Madrid

15:20 Are Elliptical Galileo Satellites Usable for RTK?  
Andrew Simsky, Dries Schellekens  
Septentrio N.V., Belgium

15:40 Machine Learning Utilization in GNSS—Use Cases, Challenges and Future Applications  
Akpojoto Siemuri, Heidi Kuusniemi, Mohammed S. Elmusrati, Petri Välisuo, Ahm Shamsuzzoha  
University of Vaasa, Finland

16:00 Galileo performance assessment for aerial navigation  
José Alberto Gonçalves<sup>1,2</sup>, Américo Magalhães<sup>1</sup>, Luisa Bastos<sup>1,2</sup>  
1) University of Porto - Science Faculty, Portugal  
2) CIIMAR - Interdisciplinary Centre of Marine and Environmental Research

4:20pm - 4:40pm Break

4:40pm - 5:20pm **SS Smartphone positioning**

Session Chair: Vincenzo Di Pietra, Politecnico di Torino

Session Chair: Paolo Dabove, Politecnico di Torino

16:40 SmartCoop Algorithm: Improving Smartphones Position Accuracy and Reliability through Collaborative Positioning  
Thomas Verheyde<sup>1</sup>, Antoine Blais<sup>2</sup>, Christophe Macabiau<sup>2</sup>, François-Xavier Marmet<sup>3</sup>

1) TésA Research Laboratory; 2) ENAC, Université de Toulouse.; 3) CNES, Centre National d'Etudes Spatiales

17:00 Assessing Galileo positioning using a smartphone in an airborne platform  
Américo da Silva Magalhães, José Alberto Gonçalves, Luísa Bastos  
Faculty of Sciences, University of Porto, Portugal

### **Thursday, June 3, 2021**

10:00am - 11:00am **SS GNSS assessment 1**

Session Chair: Peter Buist, European GNSS Agency (GSA)

Session Chair: Hillar Tork, European Commission (DG/DEFIS)

10:00 Interoperability of GNSSs for Position, Velocity and Timing  
Alessandro Caporali, Joaquin Zurutuza  
University of Padova, Italy

10:20 Analysis of Galileo NeQuick ionospheric model based on the station position error  
Anna Świątek, Leszek Jaworski, Paulina Woźniak  
Space Research Centre, Polish Academy of Sciences, Warsaw, Poland

10:40 Performance testing and runtime optimisation of an independent NeQuick-G implementation  
Nikki de Kleer, Hein Zelle  
NLR (Netherlands Aerospace Centre), the Netherlands

11:00am - 12:00pm **Keynote: Jari Saarinen**, Sensible4

Session Chair: Simona Lohan, TAU

12:00pm - 12:20pm Break

12:20pm - 1:40pm **SS GNSS assessment 2**

Session Chair: Peter Buist, European GNSS Agency (GSA)

Session Chair: Hillar Tork, European Commission (DG/DEFIS)

12:20 Galileo OS navigation performance monitoring supported by RIGTC/GOP  
Jan Dousa, Pavel Vaclavovic, Michael Kala, Petr Bezdeka, Lewen Zhao  
Research Institute of Geodesy, Topography and Cartography, Czech Republic

12:40 Improved velocity estimation in urban areas using Doppler observations  
Ankit Jain, Dennis Kulemann, Steffen Schön  
Leibniz University Hannover, Germany

13:00 REASON – Resilience and Security of Geospatial Data for Critical Infrastructures

Sanna Kaasalainen<sup>1</sup>, Maija Mäkelä<sup>1</sup>, Laura Ruotsalainen<sup>2</sup>, Titti Malmivirta<sup>2</sup>, Thomas Fordell<sup>3</sup>, Kalle Hanhijärvi<sup>3</sup>, Anders Wallin<sup>3</sup>, Thomas Lindvall<sup>3</sup>, Sergey Nikolskiy<sup>1</sup>, Martta-Kaisa Olkkonen<sup>1</sup>, Jesperi Rantanen<sup>1</sup>, Sonja Lahtinen<sup>1</sup>, Zahidul Bhuiyan<sup>1</sup>, Hannu Koivula<sup>1</sup>

1) Finnish Geospatial Research Institute, Finland

2) University of Helsinki, Finland

3) VTT MIKES, Finland

- 13:20 State of the art of the agriculture professional GNSS receivers  
Jacopo Capolicchio<sup>1</sup>, Daniele Mennuti<sup>2</sup>, Ileana Milani<sup>3</sup>, Luigi Villa<sup>4</sup>, Joaquin Reyes Gonzalez<sup>5</sup>, Martin Sunkevic<sup>5</sup>  
1) Thales Alenia Space Italia, Italy; 2) Business Integration Partners, Italy; 3) Randstad Italia, Italy; 4) Akka Italia, Italy; 5) European GNSS Agency (GSA)

1:40pm - 3:00pm Exhibit break and lunch

3:00pm - 4:00pm **LEO and Filters**

Session Chair: Robert Piché, Tampere University

- 15:00 A Review on Precise Orbit Determination of Various LEO Satellites  
Kannan Selvan, Akpo Siemuri, Heidi Kuusniemi, Petri Välisuo  
Digital Economy, University of Vaasa, Finland
- 15:20 Embedded Tightly Coupled INS/DGPS-DGAL Navigation Filter on a Mass-Market Single-Board Computer  
Maximilian Nitsch, Jan-Jöran Gehrt, Lukas Heyn, René Zweigel, Dirk Abel  
Institute of Automatic Control, RWTH Aachen University, Aachen
- 15:40 Kalman filtering with empirical noise models  
Matti Raitoharju<sup>1</sup>, Henri Nurminen<sup>2</sup>, Demet Cilden-Guler<sup>3</sup>, Simo Särkkä<sup>1</sup>  
1) Aalto University, Espoo, Finland; 2) Here, Tampere, Finland; 3) Faculty of Aeronautics and Astronautics, Istanbul Technical University, Turkey

4:00pm - 4:20pm Break

4:20pm - 5:00pm **SS Wearable computing**

Session Chair: Aleksandr Ometov, Tampere University

- 16:20 Development of Smart Shin Guards For Soccer Performance Analysis Based On MEMS Accelerometers, Machine Learning, And GNSS  
Karin Mascher, Stefan Laller, Manfred Wieser  
Graz University of Technology, Austria
- 16:40 The transferable methodologies of detection sleep disorders thanks to the actigraphy device for Parkinson's disease detection  
Justyna Anna Skibinska<sup>1,2</sup>, Radim Burget<sup>1</sup>  
1) Brno University of Technology, Czech Republic; 2) Tampere University, Finland

5:00pm - 5:20pm

***Awards and Closing***

Session Chair: Jari Nurmi, Tampere University